

Joint Estimation of RETFs and PSDs for Multi-Channel Speech Enhancement

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Introduction

• Problem

- Reverberation and ambient noise jointly present in typical acoustic environments
- Speech quality and intelligibility degradation
- Performance degradation of ASR systems

• Objective

- Develop (single- and) multi-channel joint
 dereverberation and noise reduction algorithms
- Exploit knowledge or (statistical) models of speech signals and room acoustics

• This presentation:

- Multi-channel Wiener filter (MWF) = MVDR beamformer + spectral postfilter
- → requires estimate of **relative transfer function vector** of target source and **PSDs** of target source and interference (reverberation and noise)





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Signal model

- Scenario: speech source in noisy and reverberant environment, *M* microphones
- Model in Short-Time Fourier Transform (STFT) domain:

$$y_m(k,l) = h_m(k,l) \star s(k,l) + v_m(k,l)$$

= $a_m(k,l)s(k,l) + x_{r,m}(k,l) + v_m(k,l)$
 \uparrow \uparrow \uparrow \uparrow
direct and early late ambient
reverberation reverberation noise
$$\mathbf{y}(k,l) = \mathbf{a}(k,l)x_1(k,l) + \mathbf{x}_r(k,l) + \mathbf{v}(k,l)$$

a(*k*,*l*) = vector of **relative early transfer functions (RETFs)** of target source





Multi-microphone dereverberation and noise reduction

- 1. Beamforming + spectral postfilter: VAD [18] *multiply* each time-frequency bin $\hat{\mathbf{\Gamma}}(k)$ coherence stimation with real-valued gain DOA [19] estimation MVDR [29] beamformer $y_2(n)$ $\mathbf{y}(l) = \mathbf{a}(l)x_1(l) + \mathbf{x}_r(l) + \mathbf{v}(l)$ $\tilde{x}(n)$ $\hat{s}(n)$ $y_M(n)$ $\mathbf{w}_{MWF} = \frac{(\phi_d \mathbf{\Gamma} + \mathbf{\Phi}_{\mathbf{v}})^{-1} \mathbf{a}}{\mathbf{a}^H (\phi_d \mathbf{\Gamma} + \mathbf{\Phi}_{\mathbf{v}})^{-1} \mathbf{a}} \cdot \frac{\phi_{x_1}}{\phi_{x_1} + (\mathbf{a}^H (\phi_d \mathbf{\Gamma} + \mathbf{\Phi}_{\mathbf{v}})^{-1} \mathbf{a})^{-1}}$
- 2. Reverberation and noise suppression: subtract complex-valued estimate of late reverberant and noise component

$$y_m(l) = h_m(l) \star s(l) + v_m(l)$$

$$\hat{x}_{e,1}(l) = y_1(l) - \mathbf{Y}_{\tau}(l)\mathbf{g}(l)$$





Beamforming + spectral postfilter

• Filter-and-sum structure : $z = \mathbf{w}^H \mathbf{y}$



[Doclo, Kellermann, Makino, Nordholm, IEEE Signal Processing Magazine, Mar. 2015] [Gannot, Vincent, Markovich-Golan, Ozerov, IEEE/ACM Trans. Audio, Speech and Language Processing, Apr. 2017]



Beamforming + spectral postfilter

- Filter-and-sum structure : $z = \mathbf{w}^H \mathbf{y}$ $\mathbf{y} = \mathbf{a} x_1 + \mathbf{n}$
- "Workhorse algorithm": Multi-channel Wiener filter (MWF)

Goal: estimate desired speech component in reference microphone + trade off interference (*noise and/or reverberation*) reduction and speech distortion

$$\min_{\mathbf{w}} \mathcal{E}\{|\mathbf{w}^H \mathbf{x} - x_1|^2\} + \mu \mathcal{E}\{|\mathbf{w}^H \mathbf{n}|^2\} \Rightarrow \mathbf{w}_{MWF} = (\mathbf{\Phi}_x + \mu \mathbf{\Phi}_n)^{-1} \mathbf{\Phi}_x \mathbf{e}$$

Requires estimate of covariance matrices, e.g., based on speech presence probability (SPP) or voice activity detection (VAD)

Can be decomposed as MVDR beamformer and spectral postfilter

$$\mathbf{w}_{MWF} = \underbrace{\frac{\mathbf{\Phi}_n^{-1}\mathbf{a}}{\mathbf{a}^H \mathbf{\Phi}_n^{-1}\mathbf{a}}}_{\mathbf{\Phi}_n^{-1}\mathbf{a}} \cdot \underbrace{\frac{\phi_{x_1}}{\phi_{x_1} + (\mathbf{a}^H \mathbf{\Phi}_n^{-1}\mathbf{a})^{-1}}}_{\phi_{x_1} + (\mathbf{a}^H \mathbf{\Phi}_n^{-1}\mathbf{a})^{-1}}$$

Requires estimate/model of interference covariance matrix Φ_n , estimate/model of relative (early) transfer function vector **a** of desired source, and **PSDs** of speech and interference components at MVDR output

[Doclo, Kellermann, Makino, Nordholm, IEEE Signal Processing Magazine, Mar. 2015] [Gannot, Vincent, Markovich-Golan, Ozerov, IEEE/ACM Trans. Audio, Speech and Language Processing, Apr. 2017]



Beamforming + spectral postfilter

• Signal model

 $\mathbf{y}(l) = \mathbf{a}(l)x_1(l) + \mathbf{x}_r(l) + \mathbf{v}(l)$

 $\mathbf{\Phi}_{y}(l) = \phi_{x_{1}}(l)\mathbf{a}(l)\mathbf{a}^{H}(l) + \mathbf{\Phi}_{x_{r}}(l) + \mathbf{\Phi}_{v}(l)$

Late reverberation: model as diffuse sound field $\Phi_{x_r}(l) = \phi_d(l)\Gamma$

with $\phi_d(l)$ time-varying diffuse PSD and Γ time-invariant coherence matrix (also incorporating diffuse noise !)

$$\mathbf{w}_{MWF} = \frac{(\phi_d \mathbf{\Gamma} + \mathbf{\Phi}_{\mathbf{v}})^{-1} \mathbf{a}}{\mathbf{a}^H (\phi_d \mathbf{\Gamma} + \mathbf{\Phi}_{\mathbf{v}})^{-1} \mathbf{a}} \cdot \frac{\phi_{x_1}}{\phi_{x_1} + (\mathbf{a}^H (\phi_d \mathbf{\Gamma} + \mathbf{\Phi}_{\mathbf{v}})^{-1} \mathbf{a})^{-1}}$$

• Key estimation tasks:

- **RETF vector a**(*I*): *anechoic* (based on DOA estimate) or *reverberant*
- **Diffuse/late reverberant PSD** $\phi_d(l)$: using single-channel *temporal model* (exponential decay) or based on multi-channel *diffuse sound field model*
- Noise covariance matrix: estimate (requiring VAD/SPP) or model as spatially white noise $\Phi_v(l) = \phi_v(l)\mathbf{I}$



Joint Estimation of RETF vector and PSDs

- 1. Covariance whitening (CW) method:
 - Requires estimate of noise covariance matrix

$$\hat{\Phi}_x(l) = \hat{\Phi}_y(l) - \hat{\Phi}_v(l) = \phi_{x_1}(l)\mathbf{a}(l)\mathbf{a}^H(l) + \phi_d(l)\mathbf{\Gamma}$$

• **Eigenvalue decomposition** of prewhitened signal correlation matrix

$$\hat{\boldsymbol{\Phi}}_{x}^{w}(l) = \boldsymbol{\Gamma}^{-1/2} \hat{\boldsymbol{\Phi}}_{x}(l) \boldsymbol{\Gamma}^{-H/2} = \boldsymbol{\phi}_{x_{1}}(l) \mathbf{b}(l) \mathbf{b}^{H}(l) + \boldsymbol{\phi}_{d}(l) \mathbf{I}$$

Eigenvalues: estimate of PSDs

$$\hat{\phi}_{x}(l) = \lambda_{1}\{\hat{\Phi}_{x}^{w}(l)\}
\hat{\phi}_{d}(l) = \lambda_{2}\{\hat{\Phi}_{x}^{w}(l)\} \qquad \hat{\phi}_{d,\mu}(l) = \frac{1}{M-1}(\operatorname{tr}\{\hat{\Phi}_{x}^{w}(l)\} - \lambda_{1}\{\hat{\Phi}_{x}^{w}(l)\})$$

Principal eigenvector: estimate of RETF vector

$$\hat{\mathbf{a}}(l) = \frac{\mathbf{\Gamma}^{1/2}\mathbf{u}(l)}{\mathbf{e}^T\mathbf{\Gamma}^{1/2}\mathbf{u}(l)}$$

[Markovich-Golan, Gannot, *ICASSP 2015*] [Kodrasi, Doclo, *HSCMA 2017*] [Kodrasi, Doclo, *IEEE/ACM Trans. Audio, Speech and Language Processing*, June 2018]



Joint Estimation of RETF vector and PSDs

- 2. Alternating least squares (ALS) method, minimizing Frobenius norm
 - Model noise covariance matrix + estimate noise PSD

 $\min_{\phi_{x_1}(l),\phi_d(l),\phi_v(l),\mathbf{a}(l)} ||\hat{\Phi}_y(l) - \phi_{x_1}(l)\mathbf{a}(l)\mathbf{a}^H(l) - \phi_d(l)\mathbf{\Gamma} - \phi_v(l)\Psi||_F^2$

 No closed-form solution → two-step alternating procedure (least-squares problem for PSDs, eigenvalue problem for RETF vector)





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Algorithm 1: ALS method to jointly estimate the RETF vector
and PSDs.
    Input: \Gamma(k), \Psi(k), \hat{\Phi}_{\mathbf{y}}(k,l), iterations N, init. \hat{\mathbf{a}}^{(0)}(k,1)
    Output: \hat{\mathbf{a}}_{ALS}(k,l), \hat{\phi}_{ALS}(k,l)
    for all (k,l) do
             for i=1:N do
                     compute \mathbf{A}^{(i-1)}(k,l) using (16) and \mathbf{b}^{(i-1)}(k,l) using (17)
                      \hat{\phi}_{ALS}^{(i)}(k,l) = \left(\mathbf{A}^{(i-1)}(k,l)\right)^{-1} \mathbf{b}^{(i-1)}(k,l) (15)
                     constrain \hat{\phi}^{(i)}_{ALS}(k,l) using (25)
                      \hat{\Phi}_{\mathbf{x}}^{(i)}(k,l) =
                        \hat{\hat{\Phi}}_{\mathbf{y}}(k,l) - (\hat{\phi}_{d,\mathrm{ALS}}^{(i)}(k,l)\Gamma(k) + \hat{\phi}_{v,\mathrm{ALS}}^{(i)}(k,l)\Psi(k))
                     \hat{\Phi}_{\mathbf{x}}^{(i)}(k,l) = \hat{\mathbf{N}}^{(i)}(k,l)\hat{\mathbf{\Lambda}}^{(i)}(k,l)\hat{\mathbf{N}}^{(i),H}(k,l) (EVD)
                     \hat{\mathbf{a}}_{\text{ALS}}^{(i)}(k,l) = \sqrt{\hat{\lambda}_{1}^{(i)}(k,l)/\hat{\phi}_{s,\text{ALS}}^{(i)}(k,l)}\hat{\nu}_{1}^{(i)}(k,l) (20)
             end
             \hat{\mathbf{a}}_{ALS}^{(1)}(k,l+1) = \hat{\mathbf{a}}_{ALS}^{(N)}(k,l) / (\mathbf{e}^T \hat{\mathbf{a}}_{ALS}^{(N)}(k,l)) (for next frame)
    end
```



Simulation results

1. Simulated stationary source (ACE)

- Linear microphone array (M=6, d=6cm)
- Target source at 15° (measured room impulse responses, T₆₀ ≈ 1.25 s)
- Simulated diffuse babble noise (SDR=10 dB)

2. Recorded moving source (varechoic lab)

- Linear microphone array (M=6, d=1cm)
- Moving target source ($T_{60} \approx 0.35$ s)
- Recorded pseudo-diffuse babble noise (SDR=10 dB)

Simulation parameters:

- $f_s = 16$ kHz, STFT: 64 ms, 75% overlap, Hamming window
- Γ : spherically diffuse; smoothing: 40 ms; speech PSD estimated using decision-directed approach, $G_{min} = -10 \text{ dB}$
- CW: noise covariance matrix estimated during first second; ALS: 5 iterations







Simulation results (PESQ improvement)

1. Simulated stationary source





Linear array (M=6, d=6cm), fs=16kHz, stationary source at θ =15°, perfectly diffuse babble noise (SDR=10dB), sensor noise (DNR=10dB)

2. Recorded moving source





Linear array (M=6, d=1cm), fs=16kHz, moving source θ =0° to θ =90° pseudo-diffuse babble noise (SDR=10dB), sensor noise (DNR=10dB)



Conclusions

- Multi-microphone noise reduction and dereverberation:
 - Multi-channel Wiener filter = MVDR beamformer + spectral postfilter
 - Requires estimates of (time-varying) RETF vector of target source and PSDs of target source and interference (reverberation, noise)
 - Assumption: model reverberation as diffuse sound field
- Joint RETF and PSD estimation:
 - Covariance whitening: eigenvalue decomposition of prewhitened signal correlation matrix, requires estimate of noise covariance matrix
 - Alternating least squares: minimize Frobenius norm of error covariance matrix; does not require estimate of noise covariance matrix
- Simulation results show good performance both for stationary as well as for challenging dynamic scenarios



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Questions ?